

Optimisation and Operations Research

Lecture 13: Complexity and the P vs NP problem

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Section 1

Turing machines

The Problem

- Earlier analysis essentially ignored the underlying computer
- Computation time depends a great deal on the computer
 - ▶ e.g., can it parallelise some operations?
- So we need a “universal” model computer to create formal arguments about what is possible
- Turing created one, way back when we were just inventing computing

Turing Machines

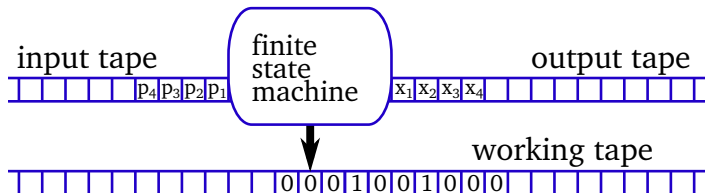
- An abstract model of a computer
- Turns out that all sufficiently complex computing systems are equivalent in the sense that they can compute the same family of functions:
 - ▶ computable functions intuitively have a finite program, that completes in a finite number of steps to the result
 - ▶ almost all functions we deal with in math are computable (though maybe not efficiently)
 - ▶ there are a few that aren't
- Turing machines have a few variants, but simplest has
 - ▶ a tape
 - ▶ a finite state machine that can write/read from the tape

Simple Turing Machine

- a tape
 - ▶ a **tape** is an idealisation of computer memory
 - ▶ imagine a strip of paper on which we can write or erase some symbols (often binary 1s and 0s)
 - ▶ the tape can be moved back and forth so that the machine can write and read any point on the tape
- a finite state machine that can write/read from each tape
 - ▶ n states, plus “halt”
 - ▶ transition function has inputs of current state and current tape value
 - ▶ transition causes three outputs:
 - ★ can write over the current bit of the tape
 - ★ it can move the tape
 - ★ the state machine’s state can change
- running the machine means setting a set of tape values, and a starting state, and then allowing transitions until “halt” is reached

Our Turing Machine

- Ours will be just a little different (but equivalent)



- Its helpful to separate inputs and outputs from working memory
 - ▶ input tape (with the input \mathbf{p} – the *program* – on it)
 - ▶ output tape (which we will write the output \mathbf{x} on)
 - ▶ a working tape
 - ▶ a finite state machine that can write/read from each tape
- We'll call this a *universal computer*
 - ▶ measure complexity by the number of state changes

Section 2

Complexity Nomenclature

Algorithm v Problem complexity

Remember that

- we start with *instances* of a class of problem of given size n
- in general think about solving using a Turing Machine
- we can measure the time of an instance, and often calculate the time of the worst case, when a particular *algorithm* is used to solve it
- we often attribute a *problem* with the complexity of the **best algorithm**, on the **worst instance**
- describe complexity with big-O notation, e.g., $O(n^2)$

General problem descriptions

Common types of (general) problem

decision : does a solution exist?

search : find a solution.

counting : how many solutions exist?

optimisation : find the best solution.

The distinction is arbitrary: *e.g.*, we can solve a decision problem by searching for a solution, but its helpful in thinking about complexity.

General problem descriptions: example 1

Example

decision : is n prime?

search : factorise n (if it is possible).

counting : how many possible factors does n have?

optimisation : find the factorisation which has the largest sum of factors.

General problem descriptions: example 2

Example

Given a set of numbers, e.g., $S = \{-7, -3, -2, 5, 8\}$

decision : does some subset of S add to give zero? **Yes.**

search : find a subset that adds to give zero: **$\{-3, -2, 5\}$**

counting : how many subsets of S add to give zero? **1?**

optimisation : find the subset that adds to zero with the least members.
 $\{-3, -2, 5\}$

General problem descriptions: example 3 (TSP)

Example

TSP (Travelling Sale-person's Problem) variants:

decision : is there a path visiting each city with distance less than k ?

search : find a path visiting each city with distance less than k .

counting : how many paths have distance less than k ?

optimisation : find the shortest path visiting all cities.

General problem descriptions: example 4 (LP)

Example

Linear programming problems:

decision : is $A\mathbf{x} \leq \mathbf{b}$ feasible?

Simplex Phase I, or is there something easier?

search : find a feasible solution to $A\mathbf{x} \leq \mathbf{b}$. Simplex Phase I

counting : how many vertices does the region defined by $A\mathbf{x} \leq \mathbf{b}$ have?

This could be hard?

optimisation : maximise $\mathbf{c}^T \mathbf{x}$ over $A\mathbf{x} \leq \mathbf{b}$. Simplex

Decision problems

Definition (Decision problem)

A *decision problem* is a problem whose answer is YES or NO.

- Can be viewed as dividing problem instances in member and non-member instances
- Avoids issues of the output size of the problem
- The alternatives above could be described as *function problems* where a more complex result is the output. It seems a richer class of problem, but can always be recast as decision problems, e.g.,

$$a \times b$$

can be recast as a set of problems “is $a \times b = c$?”

- NB: often, we solve decision problems by searching for a solution! Think of the solution as a *check*.

Tractability

Problems that can be solved in theory (e.g., given large but finite time), but which in practice take too long for their solutions to be useful, are known as *intractable* problems

We can't trivially distinguish the intractable and tractable problems, so we often divide them by their asymptotic performance into

polynomial means there is an algorithm which takes time $poly(n)$ for some polynomial $p(n)$ on inputs of length n

- remember this is the worst case performance
- write it as $O(n^k)$ for some fixed k
- polynomial time algorithms are often treated as equivalent to tractable

exponential means it takes time *at least* $2^{poly(n)}$

- grows faster than any polynomial
- exponential algorithms are assumed to be intractable

Section 3

$P \vee NP$

Deterministic and Non-Deterministic Turing Machines

- A *deterministic* Turing machine is just what we described earlier
 - ▶ given a particular input, its output is “deterministic”
 - ▶ people have built them (almost)
 - ▶ standard computers are analogous
- a *non-deterministic* Turing machine: it can have a set of rules that give more than one action for a given situation.
 - ▶ in a given state, input a given symbol, perform both A and B
 - ▶ can think of it as
 - ★ getting to try both possibilities
 - ★ being able to guess the correct branch

Non-deterministic Turing machines don't exist, but are useful for describing algorithm complexity.

P and NP

Definition (P)

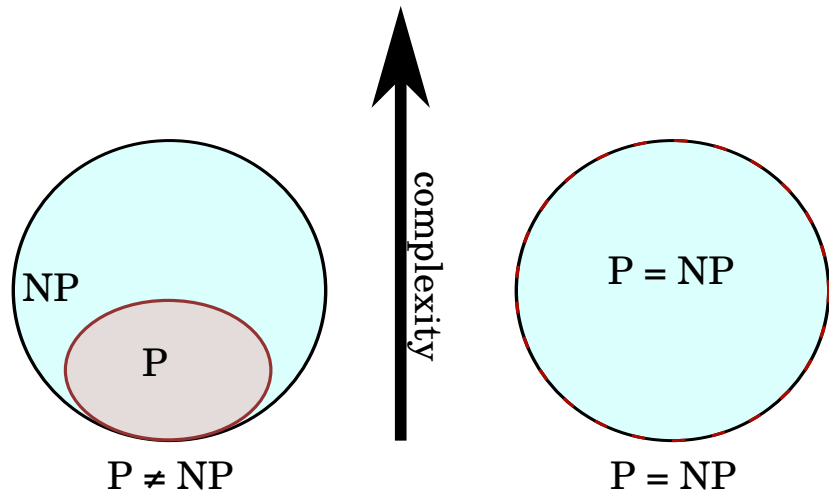
P is the set of *decision* problems that are *Polynomial time*, *i.e.*, they can be solved by a deterministic Turing machine in polynomial time.

Definition (NP)

NP is the set of *decision* problems that are *Non-deterministic Polynomial time*, *i.e.*, they can be solved by a non-deterministic Turing machine in polynomial time.

- NP does **NOT** mean Non-Polynomial
- It actually includes all polynomial-time decision problems, *i.e.*,
 $P \subset NP$
- We *don't know* if it has anything else in it
 - ▶ Is $P = NP$?
 - ▶ Win \$1,000,000 if you can answer this

Euler Diagrams



NP = Non-deterministic Polynomial time

Ways to think about NP

- NP problems have an efficient (polynomial time) *verifier*
 - ▶ computing the decision might be hard
 - ▶ but checking a YES decision is easy
 - ▶ e.g., is n prime?
 - ★ factorization might require checking all possible factors
 - ★ given two factors p, q its easy to check $p \times q = n$

assumes the YES result comes with a “proof certificate” (often a solution) which can be checked.

- They can be solved in polynomial time by a non-deterministic Turing machine using the following approach
 - 1 Guess a solution
 - 2 Check it

A non-deterministic Turing machine can make the right guess, so compute time is just the time to check the solution.

NP examples

- All P problems
- Graph isomorphism problem
- integer factorisation
- SAT

SAT

A very general class of decision problems is SAT

Definition (SAT)

A (Boolean) *satisfiability* (SAT) problem has n Boolean variables x_1, \dots, x_n and a Boolean formula ϕ involving the variables. The question is whether there is an assignment (of TRUE and FALSE) to the variables, such that $\phi(x_1, \dots, x_n) = \text{TRUE}$, i.e., we satisfy the formula.

Example

One variable x_1 and Boolean formula

$$\phi(\mathbf{x}) = x_1 \wedge \neg x_1$$

where $\wedge = \text{AND}$ and $\neg = \text{NOT}$, is *not satisfiable* because

$$\begin{aligned} \text{TRUE AND NOT TRUE} &= \text{FALSE} \\ \text{FALSE AND NOT FALSE} &= \text{FALSE} \end{aligned}$$

so there is no value of x_1 that leads to $\phi(x_1) = \text{TRUE}$.

Example

Three variables x_1 , x_2 and x_3 and Boolean formula

$$\phi(\mathbf{x}) = (x_1 \vee \neg x_2) \wedge (\neg x_1 \vee x_2 \vee x_3) \wedge \neg x_1$$

where

\vee = OR

\wedge = AND

\neg = NOT

is satisfied by $x_1 = \text{FALSE}$, $x_2 = \text{FALSE}$, and x_3 arbitrarily.

We *think* some problems in NP aren't in P

- We certainly know some problems in NP for which we have no polynomial-time algorithm *at present*
 - ▶ e.g., SAT
 - ▶ so we think these might be harder than P
 - ▶ a problem is called *NP-hard* if it is at least as hard as the hardest problem in NP
 - ▶ we'll define formally in a moment
- If $P \neq NP$ then NP-hard problems cannot be solved in polynomial time.

We *think* some problems in NP aren't in P

If $P = NP$, then the world would be a profoundly different place than we usually assume it to be. There would be no special value in “creative leaps,” no fundamental gap between solving a problem and recognizing the solution once it's found. Everyone who could appreciate a symphony would be Mozart; everyone who could follow a step-by-step argument would be Gauss; everyone who could recognize a good investment strategy would be Warren Buffett. It's possible to put the point in Darwinian terms: if this is the sort of universe we inhabited, why wouldn't we already have evolved to take advantage of it?

Scott Aaronson

<http://www.scottaaronson.com/blog/?p=122>

NP-hard definitions

Definition

A problem A can be reduced to B if we could solve A using the algorithm that solves B as a subroutine.

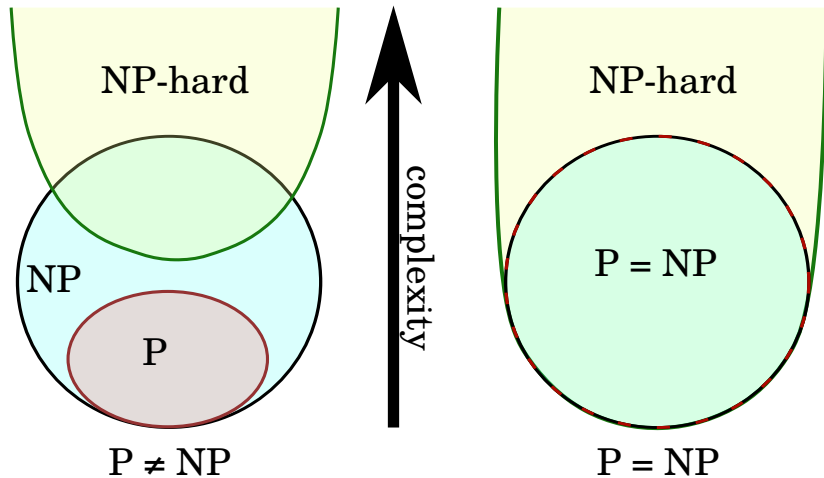
- If we have a polynomial time reduction (that is one that can be done in polynomial time, excluding the time in the subroutine) then we can efficiently convert one problem into the other.
- So A is no more difficult than B .

Definition (NP-hard)

A problem H is NP-hard if every problem L in NP can be *reduced* in polynomial time to H .

- So H is at least as hard as any L in NP.
- Note that an NP-hard problem isn't necessarily in NP!

Euler Diagrams



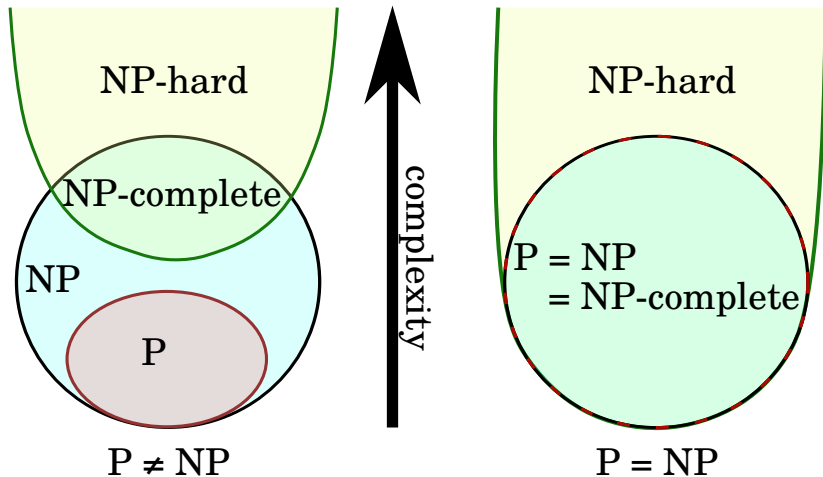
NP-complete

Definition (NP-complete)

A problem that is in NP, and in NP-hard is called NP-complete.

- A problem p in NP is NP-complete if every other problem in NP can be reduced to p in polynomial time.
- A decision problem is NP-complete if it is in NP, and every problem in NP is reducible to it.
- Cook's theorem: the Boolean satisfiability problem (SAT) is NP-complete
 - ▶ so many proofs of NP-completeness show SAT can be reduced to the problem

Euler Diagrams



Example NP-complete problems

- SAT (and many variants)
- *Binary linear programming*
- Set covering
- Hamiltonian circuit
- Graph colouring
- Bin-packing and Knapsack
- TSP problem
- Many others

NB: decision versions of the above where its not obvious.

Other important chunks

- If a decision problem is NP-complete, then its optimisation version is NP-hard
- Weirdest case I know
 - ▶ The graph isomorphism problem
 - ★ is graph G_1 isomorphic to G_2
 - ★ its in NP
 - ★ its suspected to be neither in P or NP-complete
 - ★ very recently a *quasi-polynomial* time algorithm was found
- call these NPI = NP-intermediate
 - ▶ in NP, but not in P or NP-complete
- There are NP-hard problems that are not NP-complete
 - ▶ e.g., the halting problem
 - ★ given a program and its input, will it run forever?
 - ★ its undecidable (so not in NP)
 - ★ SAT can be reduced to the halting problem by writing Turing machine program that tries all values

Misconceptions

- NP-complete problems are not the “hardest”
 - ▶ they are in NP – some problems aren't!
 - ★ some problems can't even be verified in polynomial time
 - ▶ decision problems in Presburger arithmetic can take $O(2^{2^n})$, *i.e.*, double exponential time
- Not all *instances* of NP-complete problems are hard
 - ▶ many (even most) instances of some NP-complete problems can be solved in polynomial time
 - ▶ complexity refers to worst case
- Problems with an exponential number of possibilities are not all NP-complete
 - ▶ counter-example: shortest paths is solvable in $O(n \log n)$ time

Takeaways

- We talked about complexity *classes*
 - ▶ P
 - ▶ NP
 - ▶ NP-complete
 - ▶ NP-hard

we don't know if $P = NP$

- *At the moment*, we can't solve an NP-complete problem in *guaranteed* polynomial time
 - ▶ integer programming is, in general, NP-complete
 - ★ some of these problems are currently intractable
 - ★ but some restricted subsets of integer programming problems might have polynomial time algorithms
 - ★ others might have good approximations
 - ▶ in general, though, we are going to have to be a bit more clever when tackling integer programming problems
 - ★ there is no “one-size-fits-all” like the Simplex for LPs

Something to watch

Watch `https:`

`//www.youtube.com/watch?v=YX40hbAHx3s&feature=youtu.be`

Further reading I